

# Basis Vectors for a Radially Moving Point Source

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In Boyer-Lindquist co-ordinates, the Kerr metric is written

$$ds^2 = c^2 \left( 1 - \frac{2\mu r}{\rho^2} \right) dt^2 + \frac{4\mu a c r \sin^2 \theta}{\rho^2} dt d\varphi - \frac{\rho^2}{\Delta} dr^2 - \rho^2 d\theta^2 - \left( r^2 + a^2 + \frac{2\mu a^2 r \sin^2 \theta}{\rho^2} \right) \sin^2 \theta d\varphi^2$$

where,

$$\begin{aligned} \mu &\equiv \frac{GM}{c^2} \\ \rho^2 &\equiv r^2 + a^2 \cos^2 \theta \\ \Delta &\equiv r^2 - 2\mu r + a^2 \end{aligned}$$

We wish to calculate the tetrad of basis vectors,  $\{e'_{(a)}\}$ , describing the locally flat instantaneous rest frame of an observer (*i.e.* a point source) moving radially in the Kerr spacetime around a black hole.

The spacetime in the observer's rest frame reduces to Minkowski space, described by the metric

$$e'_{(a)} \cdot e'_{(b)} = \eta_{ab} \quad (1)$$

Where the Minkowski metric  $[\eta_{ab}] = \text{diag}(1, -1, -1, -1)$ .

For a radially moving observer, travelling at velocity  $\frac{dr}{dt} = V$ , the 4-velocity can be written (in Boyer-Lindquist co-ordinates)

$$[u^\mu] = (u^t, u^r, 0, 0) = u^t (1, V, 0, 0) \quad (2)$$

Since the observer is at rest in its own rest frame, the spatial components of the 4-velocity must be zero in that frame, hence the observer's timelike basis vector is parallel to the 4-velocity.  $u^t$  is found by imposing the normalisation condition on the 4-velocity that  $|\mathbf{u}| = c$  and working in natural units with  $\mu = c = 1$  will result in a timelike unit vector.

$$\begin{aligned} \mathbf{u} \cdot \mathbf{u} &= 1 \\ g_{\mu\nu} u^\mu u^\nu &= 1 \end{aligned}$$

$$g_{tt} (u^t)^2 + g_{rr} (u^r)^2 = 1$$

$$g_{tt} (u^t)^2 + g_{rr} V^2 (u^t)^2 = 1$$

Hence,

$$u^t = \frac{1}{\sqrt{g_{tt} + g_{rr} V^2}} \quad (3)$$

And the timelike basis vector is given by

$$\mathbf{e}'_{(t)} = \mathbf{u} = \frac{1}{\sqrt{g_{tt} + g_{rr} V^2}} (1, V, 0, 0) \quad (4)$$

Given that the 4-velocity has no component in the  $\theta$  direction, it can be seen from the metric that a basis vector can be found, that is orthogonal to those in the other co-ordinates, of the form

$$\mathbf{e}'_{(2)} = (0, 0, e'_{(2)}{}^\theta, 0)$$

And the normalisation condition,  $\mathbf{e}'_{(2)} \cdot \mathbf{e}'_{(2)}$  gives

$$\mathbf{e}'_{(2)} = \left(0, 0, \frac{1}{\rho}, 0\right) \quad (5)$$

In order to find a basis vector,  $\mathbf{e}'_{(3)}$  corresponding to the radial direction, we note that the timelike basis vector has components in the  $t$  and  $r$  directions and hence try to find an orthogonal basis vector of the form

$$\mathbf{e}'_{(3)} = (e'_{(3)}{}^t, e'_{(3)}{}^r, 0, 0)$$

To be orthogonal to  $\mathbf{e}'_{(t)}$ ,

$$\mathbf{e}'_{(t)} \cdot \mathbf{e}'_{(3)} = 0$$

$$g_{tt} e'_{(t)}{}^t e'_{(3)}{}^t + g_{rr} e'_{(t)}{}^r e'_{(3)}{}^r = 0$$

$$e'_{(3)}{}^r = e'_{(3)}{}^t \frac{g_{tt}}{-g_{rr}} \frac{e'_{(t)}{}^t}{e'_{(t)}{}^r}$$

Substituting  $e'_{(t)}{}^r = V e'_{(t)}{}^t$ ,

$$e'_{(3)}{}^r = e'_{(3)}{}^t \frac{g_{tt}}{-g_{rr}} \frac{1}{V}$$

And to normalise,

$$\mathbf{e}'_{(3)} \cdot \mathbf{e}'_{(3)} = -1$$

$$\begin{aligned} g_{tt} \left( e_{(3)}^t \right)^2 + g_{rr} \left( e_{(3)}^r \right)^2 &= -1 \\ g_{tt} \left( e_{(3)}^t \right)^2 + g_{rr} \left( e_{(3)}^t \right)^2 \left( \frac{g_{tt}}{-g_{rr}} \right) \frac{1}{V^2} &= -1 \end{aligned}$$

$$e_{(3)}^t = \sqrt{\frac{-g_{rr}}{g_{tt}}} \frac{V}{\sqrt{g_{tt} + g_{rr} V^2}} \quad (6)$$

And

$$e_{(3)}^r = \sqrt{\frac{g_{tt}}{-g_{rr}}} \frac{1}{\sqrt{g_{tt} + g_{rr} V^2}} \quad (7)$$

Hence,

$$\boxed{\mathbf{e}'_{(3)} = \left( \sqrt{\frac{-g_{rr}}{g_{tt}}} \frac{V}{\sqrt{g_{tt} + g_{rr} V^2}}, \sqrt{\frac{g_{tt}}{-g_{rr}}} \frac{1}{\sqrt{g_{tt} + g_{rr} V^2}}, 0, 0 \right)}$$

Finally, to ensure orthogonality with the timelike and radial basis vectors, the fourth basis vector (corresponding to the azimuthal direction) could have components in the  $t$ ,  $r$  and  $\varphi$  directions.

$$\mathbf{e}'_{(1)} = \left( e_{(1)}^t, e_{(1)}^r, 0, e_{(1)}^\varphi \right)$$

Orthogonality with the timelike basis vector gives

$$\mathbf{e}'_{(t)} \cdot \mathbf{e}'_{(1)} = 0$$

$$\begin{aligned} g_{tt} e_{(1)}^t e_{(1)}^t + g_{t\varphi} e_{(1)}^t e_{(1)}^\varphi + g_{rr} e_{(1)}^r e_{(1)}^r &= 0 \\ g_{tt} e_{(1)}^t e_{(1)}^t + g_{t\varphi} e_{(1)}^t e_{(1)}^\varphi + g_{rr} V e_{(1)}^t e_{(1)}^r &= 0 \end{aligned}$$

$$e_{(1)}^t = - \frac{\left( g_{t\varphi} e_{(1)}^\varphi + g_{rr} V e_{(1)}^r \right)}{g_{tt}} \quad (8)$$

And orthogonality with  $\mathbf{e}'_{(3)}$ ,

$$\mathbf{e}'_{(3)} \cdot \mathbf{e}'_{(1)} = 0$$

$$g_{tt} e_{(3)}^t e_{(1)}^t + g_{t\varphi} e_{(3)}^t e_{(1)}^\varphi + g_{rr} e_{(3)}^r e_{(1)}^r = 0$$

Equation 8 gives

$$-e_{(3)}^t \left( g_{t\varphi} e_{(1)}^\varphi + g_{rr} V e_{(1)}^r \right) + g_{t\varphi} e_{(3)}^t e_{(1)}^\varphi + g_{rr} e_{(3)}^r e_{(1)}^r = 0$$

$$g_{rr} e_{(1)}^r \left( e_{(3)}^r - V e_{(3)}^t \right) = 0$$

Which requires

$$e_{(1)}^r = 0 \quad (9)$$

Hence, Equation 8 simplifies to

$$e_{(1)}^t = -\frac{g_{t\varphi}}{g_{tt}} e_{(1)}^\varphi \quad (10)$$

Lastly, normalising this basis vector,

$$\mathbf{e}'_{(1)} \cdot \mathbf{e}'_{(1)} = -1$$

$$g_{tt} \left( e_{(1)}^t \right)^2 + 2g_{t\varphi} e_{(1)}^t e_{(1)}^\varphi + g_{\varphi\varphi} \left( e_{(1)}^\varphi \right)^2 = -1$$

Substituting for  $e_{(1)}^t$ ,

$$\frac{g_{t\varphi}^2}{g_{tt}} \left( e_{(1)}^\varphi \right)^2 - 2\frac{g_{t\varphi}^2}{g_{tt}} \left( e_{(1)}^\varphi \right)^2 + g_{\varphi\varphi} \left( e_{(1)}^\varphi \right)^2 = -1$$

$$-\frac{g_{t\varphi}^2}{g_{tt}} \left( e_{(1)}^\varphi \right)^2 + g_{\varphi\varphi} \left( e_{(1)}^\varphi \right)^2 = -1$$

Giving

$$e_{(1)}^\varphi = \sqrt{\frac{g_{tt}}{g_{t\varphi}^2 - g_{tt}g_{\varphi\varphi}}} \quad (11)$$

and

$$e_{(1)}^t = -\frac{g_{t\varphi}}{g_{tt}} \sqrt{\frac{g_{tt}}{g_{t\varphi}^2 - g_{tt}g_{\varphi\varphi}}} \quad (12)$$

Hence, the tetrad of basis vectors describing the rest frame of a point source moving radially in the Kerr spacetime are given by

$$\begin{aligned} \mathbf{e}'_{(t)} &= \frac{1}{\sqrt{g_{tt} + g_{rr}V^2}} (1, V, 0, 0) \\ e_{(1)}^t &= \sqrt{\frac{g_{tt}}{g_{t\varphi}^2 - g_{tt}g_{\varphi\varphi}}} \left( -\frac{g_{t\varphi}}{g_{tt}}, 0, 0, 1 \right) \\ \mathbf{e}'_{(2)} &= \left( 0, 0, \frac{1}{\rho}, 0 \right) \\ \mathbf{e}'_{(3)} &= \left( \sqrt{\frac{-g_{rr}}{g_{tt}}} \frac{V}{\sqrt{g_{tt} + g_{rr}V^2}}, \sqrt{\frac{g_{tt}}{-g_{rr}}} \frac{1}{\sqrt{g_{tt} + g_{rr}V^2}}, 0, 0 \right) \end{aligned}$$